

# Resilient distributed routing in dynamical flow networks

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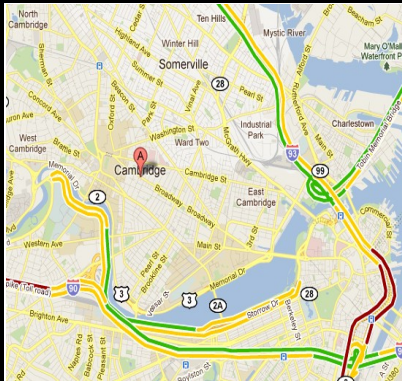
LCCC workshop on Information and Control in Networks  
Lund, October 19, 2012

joint work with: K. Savla, D. Acemoglu, M. Dahleh, and  
E. Frazzoli at MIT, E. Lovisari at Lund Automatic Control

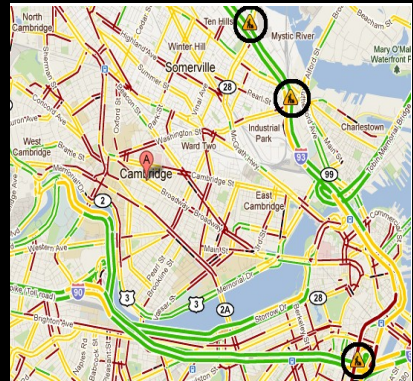
# Resilient infrastructure networks

- ▶ good in business as usual, prone to disruptions
- ▶ cascade effects

⇒ network vulnerability  $\gg \sum$  component vulnerabilities



Typical Monday at 18:30



Monday, July 11, 2011, at 18:30

# Static flow networks

di-graph  $(\mathcal{V}, \mathcal{E})$

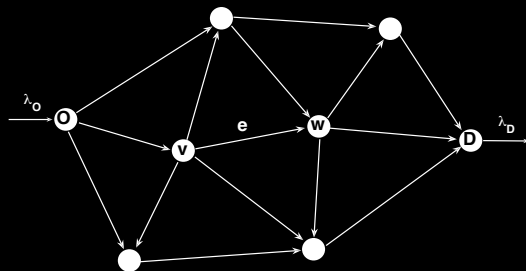
origin  $O$

destination  $D$

capacities  $C_e > 0$

$\mathcal{E}_v^+ = \{\text{out-links of } v\}$

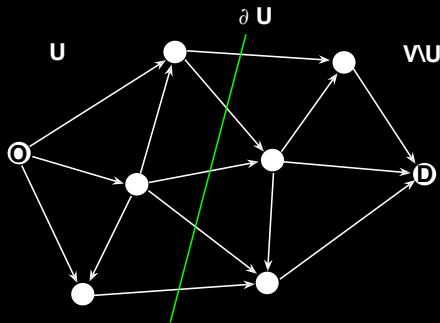
$\mathcal{E}_v^- = \{\text{in-links of } v\}$



► equilibrium flow:  $f = \{f_e\}$  such that  $0 \leq f_e < C_e$  and

$$\sum_{e \in \mathcal{E}_v^-} f_e = \sum_{e \in \mathcal{E}_v^+} f_e \quad \forall v \neq O, D$$

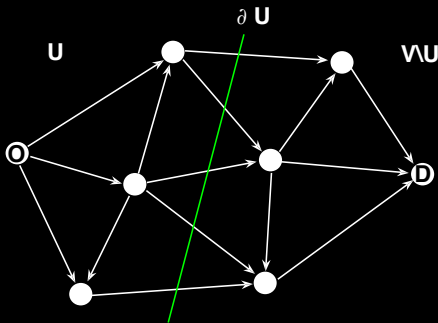
# Max-flow min-cut theorem



min-cut capacity:  $C := \min_{\text{O-D cut } \mathcal{U}} \sum_{e \in \mathcal{U}^+} C_e$

$\exists$  equilibrium flow  $f$  :  $\sum_{e \in \mathcal{E}_O^+} f_e = \lambda_O \iff C - \lambda_O > 0$

# Max-flow min-cut theorem

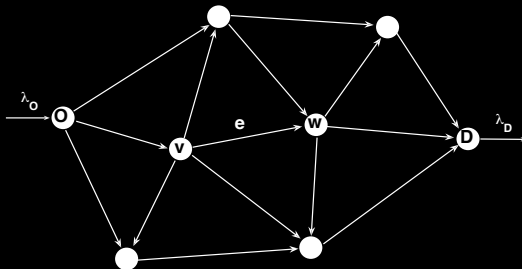


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$\exists$  equilibrium flow  $f$  :  $\sum_{e \in \mathcal{E}_O^+} f_e = \lambda_O \iff C - \lambda_O > 0$

- ▶ static, centralized, global information

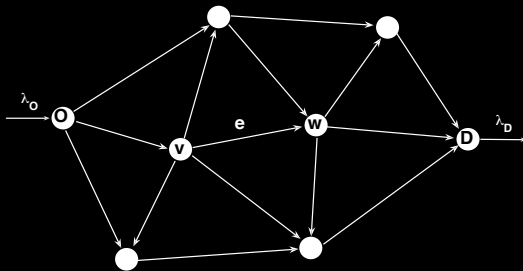
# Dynamical flow networks



$$\frac{d}{dt} \rho_e = \lambda_v G_e^v - f_e$$

$\uparrow$                        $\uparrow$                        $\uparrow$                        $\uparrow$   
 density                      flow                      fraction                      outflow  
 on  $v$                       through                      routed                      of  $e$   
 $v$                        $v$                       to  $e$

# Dynamical flow networks



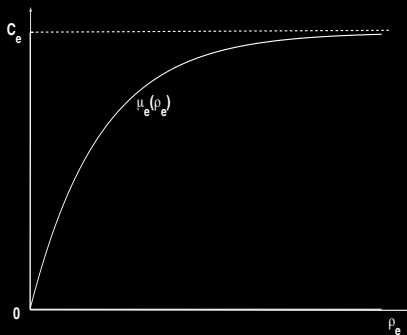
$$\frac{d}{dt} \rho_e = \lambda_v G_e^v - f_e$$

$$\text{(cf. with } \frac{\partial}{\partial t} \rho = -\nabla_x \cdot f \text{)}$$

# Flow function

$$\forall e \in \mathcal{E}$$

$$f_e = \mu_e(\rho_e)$$



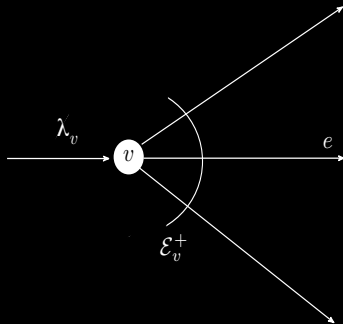
$$\mu_e(0) = 0 \quad \sup_{\rho_e \geq 0} \mu_e(\rho_e) = C_e$$

$$\frac{d}{d\rho_e} \mu_e > 0$$



# Distributed routing

$$\lambda_v = \sum_{e \in \mathcal{E}_v^-} f_e \text{ total flow through } v$$



$G_e^v$  = fraction of  $\lambda_v$  routed to  $e$

**local** information:  $\rho^v = \{\rho_e : e \in \mathcal{E}_v^+\}$

$$G^v : \mathbb{R}_+^{\mathcal{E}_v^+} \rightarrow \mathcal{P}(\mathcal{E}_v^+)$$

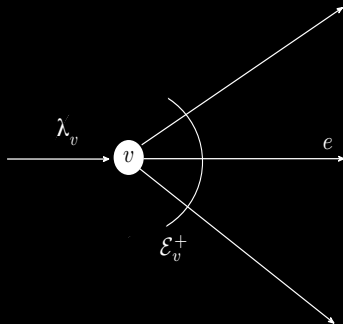


# Locally responsive distributed policies

$$G^v : \mathbb{R}_+^{\mathcal{E}_v^+} \rightarrow \mathcal{P}(\mathcal{E}_v^+)$$

$$(i) \quad \frac{\partial}{\partial \rho_j} G_e^v \geq 0 \quad \forall e \neq j \in \mathcal{E}_v^+$$

$$(ii) \quad \rho_e \rightarrow \infty \quad \Rightarrow \quad G_e^v(\rho^v) \rightarrow 0$$



## Locally responsive distributed policies

$$G^v : \mathbb{R}_+^{\mathcal{E}_v^+} \rightarrow \mathcal{P}(\mathcal{E}_v^+)$$

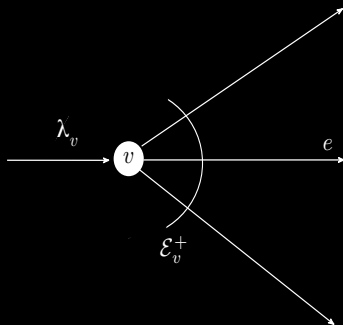
$$(i) \quad \frac{\partial}{\partial \rho_j} G_e^v \geq 0 \quad \forall e \neq j \in \mathcal{E}_v^+$$

$$(ii) \quad \rho_e \rightarrow \infty \Rightarrow G_e^v(\rho^v) \rightarrow 0$$

Ex.: i-logit

$$G_e^v(\rho^v) \propto \alpha_e \exp(-\beta \rho_e)$$

$$\beta > 0, \quad \alpha \in \mathbb{R}_+^{\mathcal{E}_v^+}$$

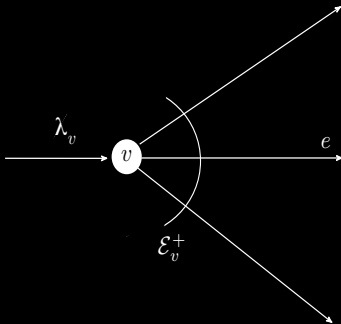


# Locally responsive distributed policies

$$G^v : \mathbb{R}_+^{\mathcal{E}_v^+} \rightarrow \mathcal{P}(\mathcal{E}_v^+)$$

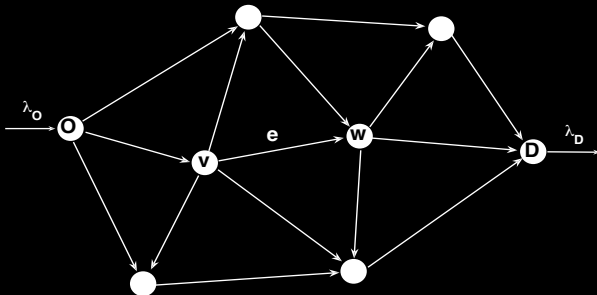
$$(i) \quad \frac{\partial}{\partial \rho_j} G_e^v \geq 0 \quad \forall e \neq j \in \mathcal{E}_v^+$$

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- (i)  $\Rightarrow$  network is monotone (i.e., Jacobian is Metzler)  $\Rightarrow \dots$   
 $\Rightarrow \dots \parallel \parallel_1$  contraction  $\Rightarrow \lim_{t \rightarrow \infty} \lambda_D(t)$  independent of  $\rho(0)$

# Dynamical flow networks



$$\frac{d}{dt}\rho_e = \lambda_v G_e^v(\rho^v) - \mu_e(\rho_e) \quad e \in \mathcal{E}_v^+, v \in \mathcal{V} \setminus \{D\}$$

transferring if  $\lim_{t \rightarrow \infty} \lambda_D(t) = \lambda_O$

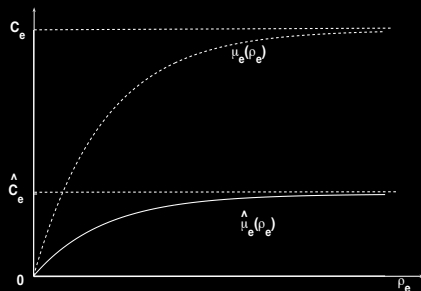
# Perturbed dynamical flow networks

Perturbation :  $\forall e \in \mathcal{E}$

$$\mu_e(\rho_e)$$

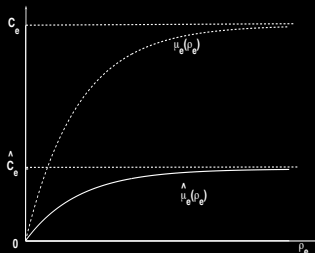
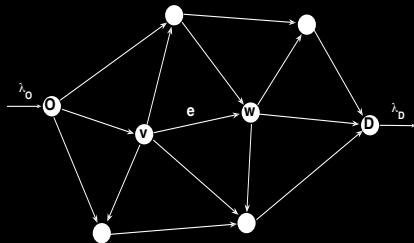
↓

$$\tilde{\mu}_e(\rho_e) \leq \mu_e(\rho_e)$$



Magnitude  $\delta := \sum_e \delta_e = \sum_e \|\mu_e(\cdot) - \tilde{\mu}_e(\cdot)\|_\infty$

# Margin of resilience



perturbed network: 
$$\frac{d}{dt} \tilde{\rho}_e = \tilde{\lambda}_v G_e^v(\tilde{\rho}^v) - \tilde{\mu}_e(\tilde{\rho}_e) \quad e \in \mathcal{E}_v^+, v \neq D$$

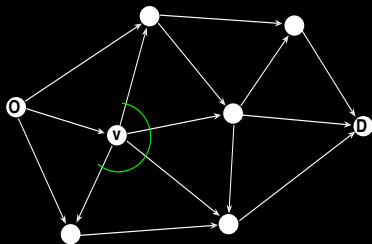
$\gamma := \inf \text{magnitude of disruption s.t. } \lim_{t \rightarrow +\infty} \tilde{\lambda}_D(t) < \lambda_O$

## Optimal resilience

residual node capacity

for limit flow  $f^*$

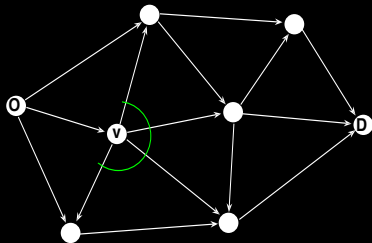
$$R(f^*) := \min_{v \neq D} \sum_{e \in \mathcal{E}_v^+} C_e - f_e^*$$





## Optimal resilience

$$R(f^*) := \min_{v \neq D} \sum_{e \in \mathcal{E}_v^+} C_e - f_e^*$$



**Theorem:** acyclic network, limit flow  $f^*$

1. distributed routing

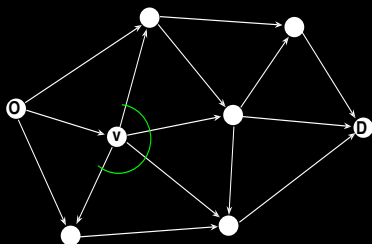
$$\gamma \leq R(f^*)$$

2. locally responsive routing  $\Rightarrow f^*$  globally attractive

$$\gamma = R(f^*)$$

## Optimal resilience (cont'd)

$$R(f^*) := \min_{v \neq D} \sum_{e \in \mathcal{E}_v^+} C_e - f_e^*$$

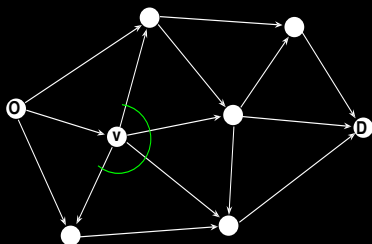


- ▶  $1 \leq \frac{C - \lambda_O}{R(f^*)}$  can be arbitrarily large

local information constraint  $\implies$  resilience loss

## Optimal resilience (cont'd)

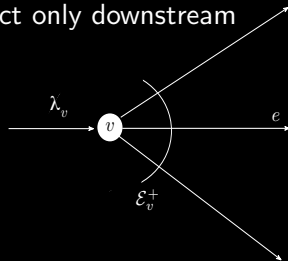
$$R(f^*) := \min_{v \neq D} \sum_{e \in \mathcal{E}_v^+} C_e - f_e^*$$



- ▶ perturbations and distributed routing effect only downstream
- ▶ locally responsive policies



locally optimal load rebalance



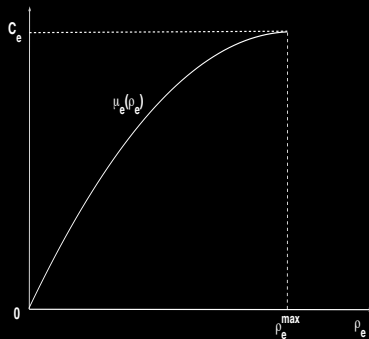
# Bounded density capacities

$$0 < \rho_e^{\max} < +\infty$$

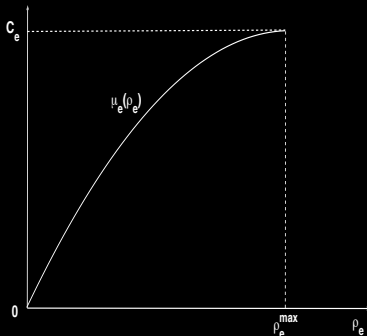
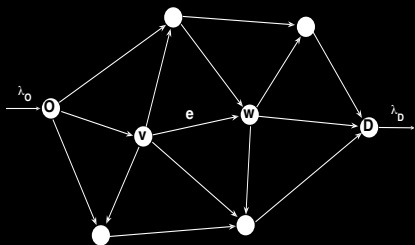
$$\mu_e(0) = 0 \quad \mu_e(\rho_e^-) = C_e$$

$$\mu_e'(\rho_e) > 0 \quad \forall \rho_e \in (0, \rho_e^{\max})$$

$$\mu_e(\rho_e) = 0 \quad \forall \rho_e \geq C_e$$



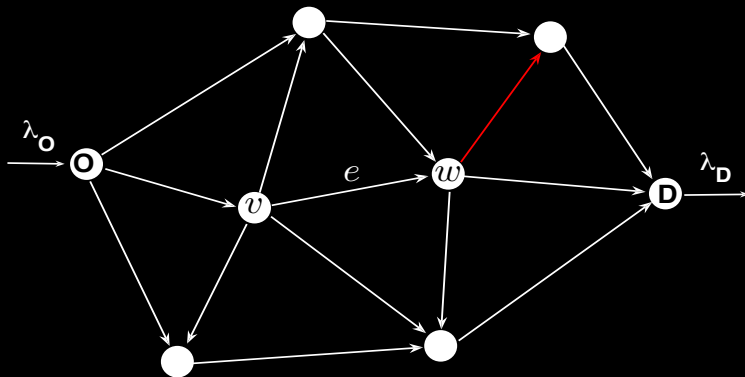
## Bounded density capacities



$$e = (v, w) \Rightarrow \frac{d}{dt} \rho_e = \chi_v(t) \lambda_v G_e^v(\rho^v) - \chi_w(t) \mu_e(\rho_e)$$

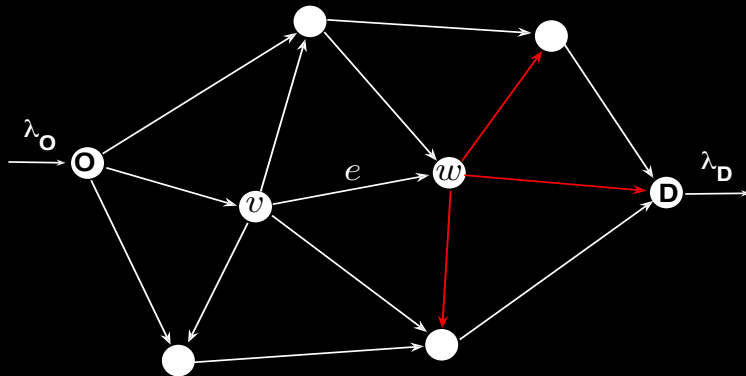
$$\chi_v(t) := 1 - \prod_{e \in \mathcal{E}_v^+} (1 - \xi_e(t)) \quad \xi_e(t) := \mathbb{1}_{[0, \rho_e^{\max})}(\rho_e)$$

## Cascade propagation mechanism



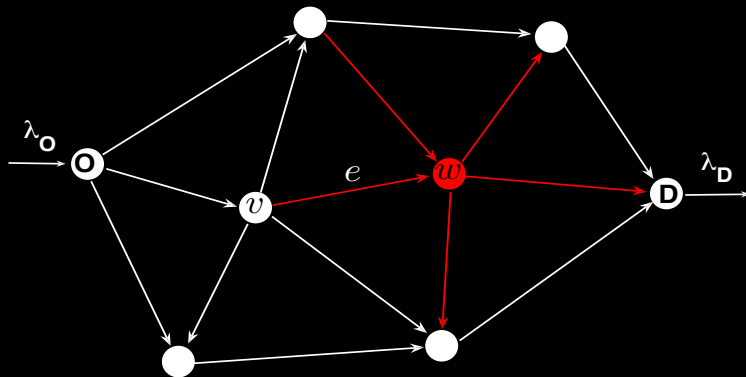
Perturbation localized on  $\mathcal{E}_w^+$ , such that  $\sum_{\mathcal{E}_w^+} \tilde{c}_e < \lambda_w^*$

## Cascade propagation mechanism



Node  $w$  overloaded  $\Rightarrow$  every  $e \in \mathcal{E}_w^+$  drops

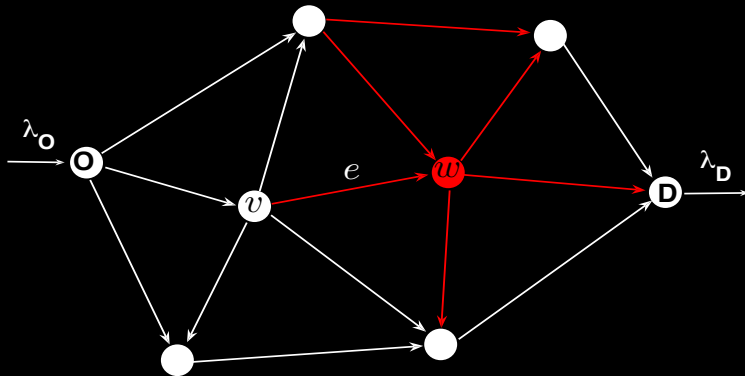
## Cascade propagation mechanism



Hence  $w$  drops together with all  $e \in \mathcal{E}_w^-$

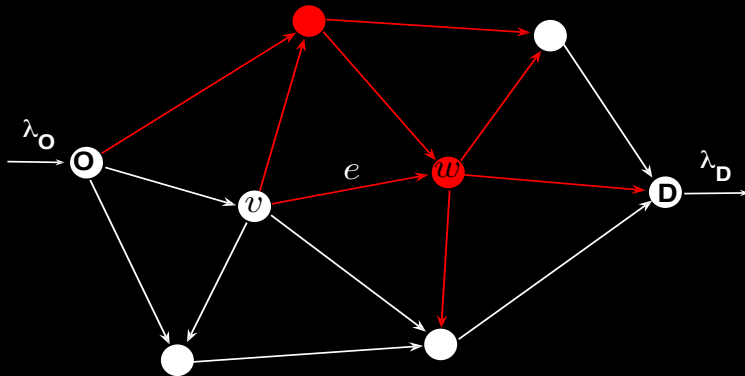


## Cascade propagation mechanism



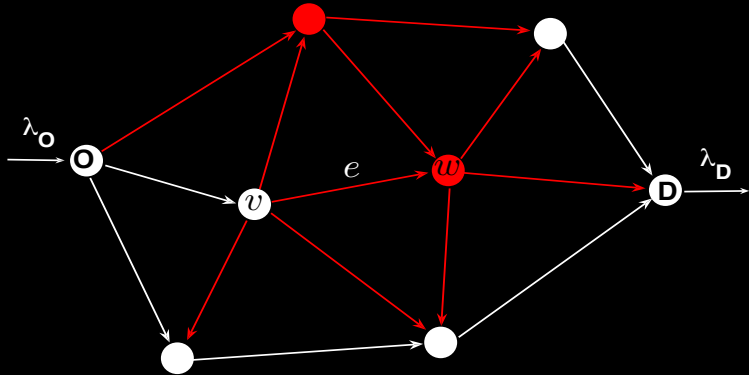
Possibly other nodes downstream become overloaded...

# Cascade propagation mechanism



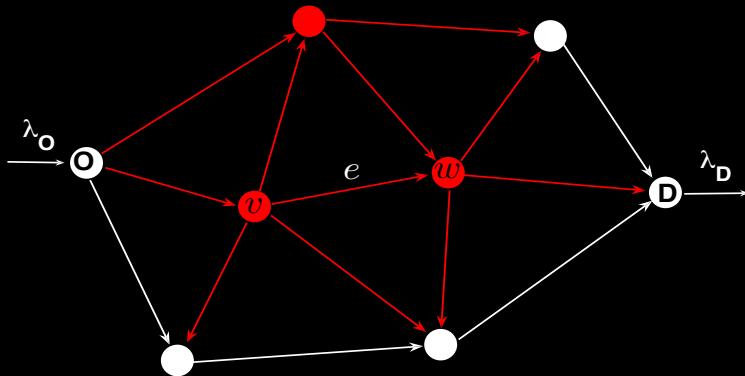
...and eventually drop

## Cascade propagation mechanism



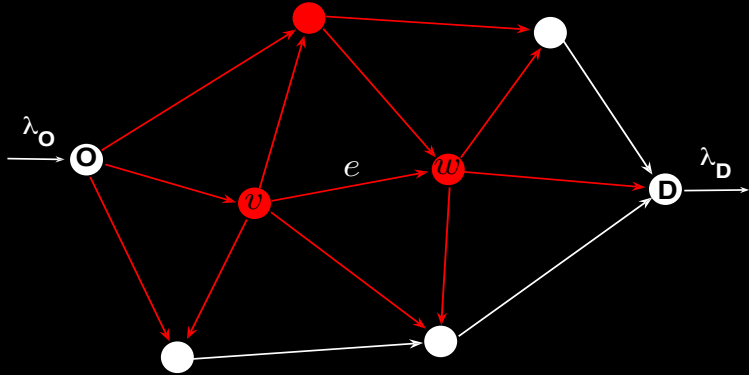
Either a new equilibrium flow is eventually achieved

# Cascade propagation mechanism



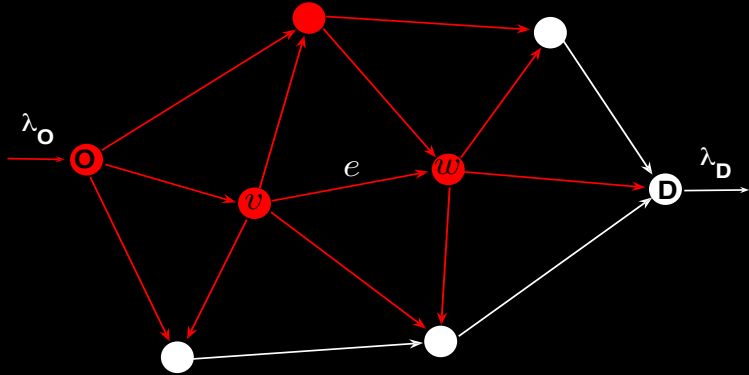
...or not.

# Cascade propagation mechanism



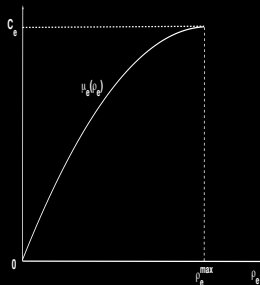
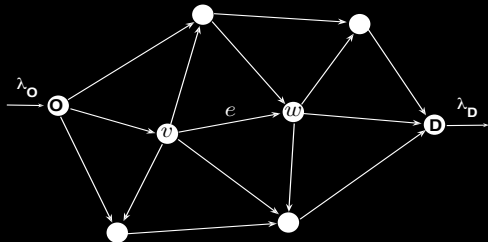
If the perturbation overloads the origin...

## Cascade propagation mechanism



... no more flow passes through the network.

# Dynamical flow networks with bounded density



**Theorem:**  $\rho_e^{\max} < +\infty \quad \forall e \implies \lim_{t \rightarrow \infty} \lambda_D(t) \in \{0, \lambda_O\}$

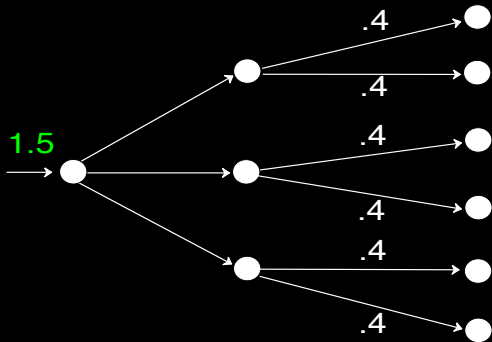
1 acyclic network, any distributed routing

$$\gamma \leq \Gamma(f^*) \quad \Gamma(f^*) := \dots \text{ backward induction}$$

2 locally responsive routing,  $d_v^+ \leq 2 \implies \gamma = \Gamma(f^*)$

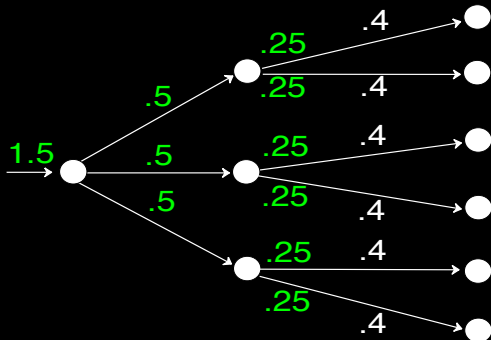
3 locally responsive routing  $\implies \gamma \geq R(f^*)$

## Dynamical flow networks with bounded density

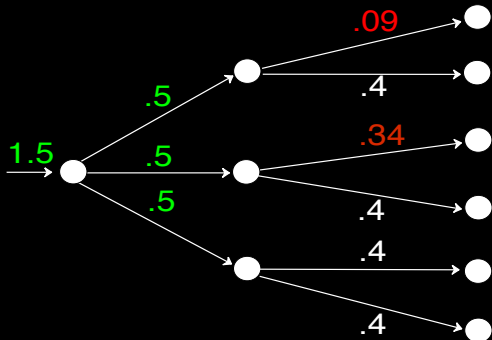




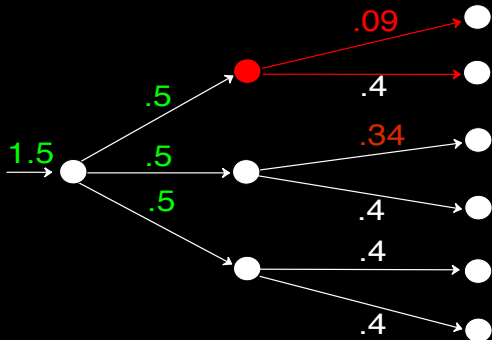
## Dynamical flow networks with bounded density



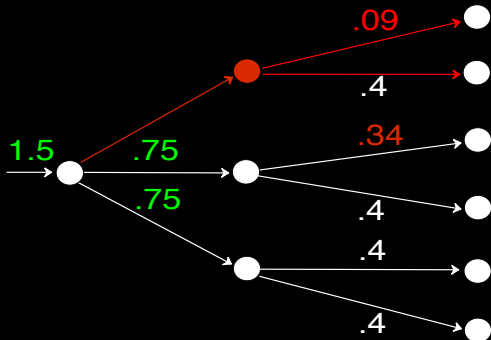
## Dynamical flow networks with bounded density



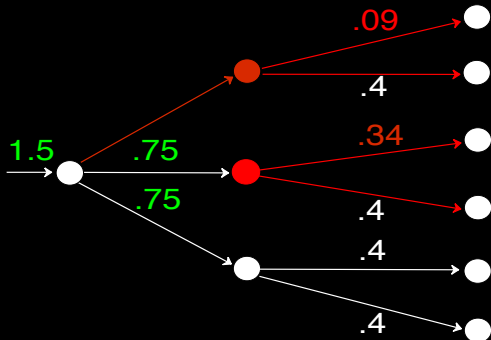
## Dynamical flow networks with bounded density



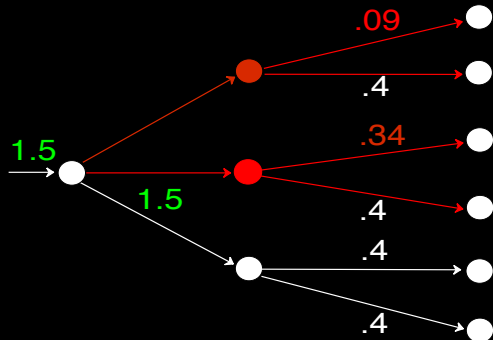
## Dynamical flow networks with bounded density



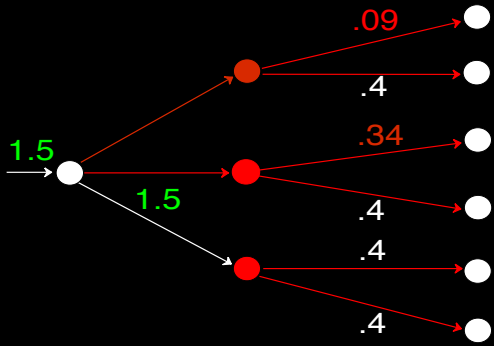
## Dynamical flow networks with bounded density



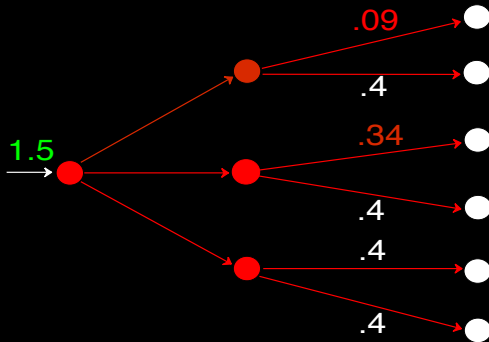
# Dynamical flow networks with bounded density



# Dynamical flow networks with bounded density



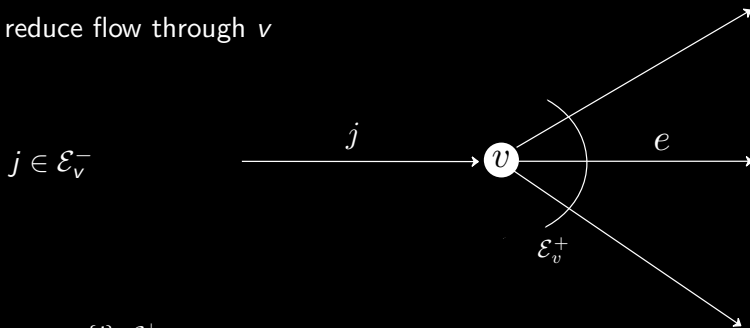
# Dynamical flow networks with bounded density





## Slowing down local flow

can reduce flow through  $v$

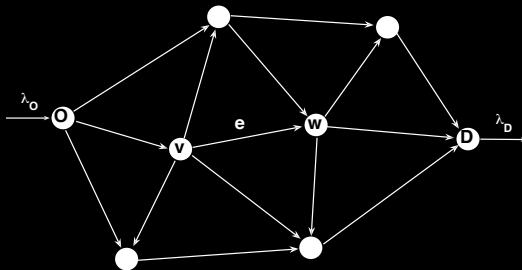


$$G^j : \mathbb{R}_+^{\{j\} \cup \mathcal{E}_v^+} \longrightarrow \mathcal{P}(\{j\} \cup \mathcal{E}_v^+)$$

$G_j^j(\rho_j, \rho^v) :=$  fraction of flow kept on  $j$

$1 - G_j^j(\rho_j, \rho^v) :=$  fraction of flow allowed through  $v$

## Slowing down achieves capacity

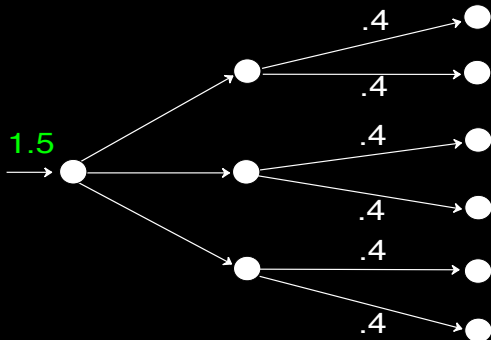


**Theorem:** Acyclic network, locally responsive policy

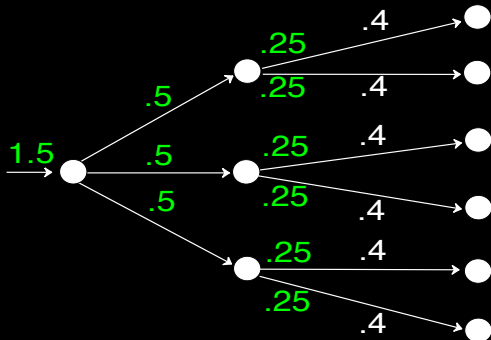
$$\gamma = C - \lambda_O$$

both with finite and infinite  $\rho_e^{\max}$

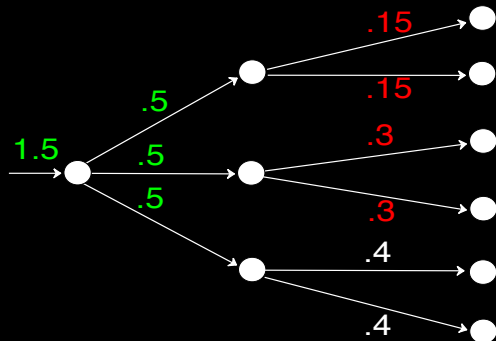
## Dynamical flow networks with bounded density



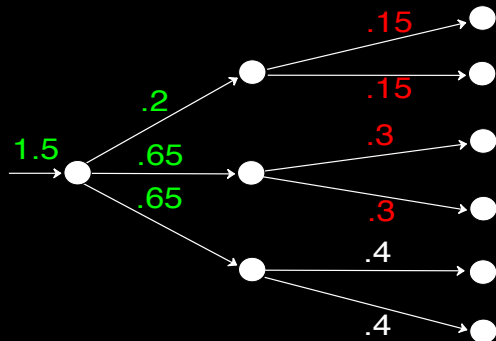
## Dynamical flow networks with bounded density



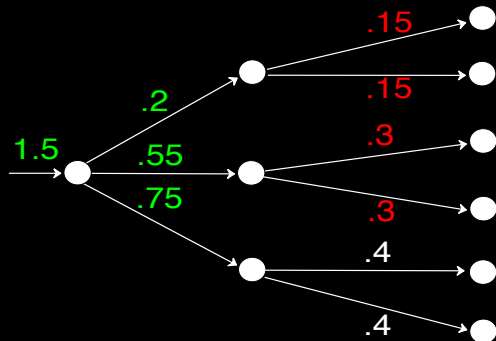
## Dynamical flow networks with bounded density



## Dynamical flow networks with bounded density



## Dynamical flow networks with bounded density



# Conclusion

## Summary

- ▶ robust distributed routing for dynamical flow networks
- ▶ margins of resilience
- ▶ role of cascades

## Current/future directions

- ▶ cycles
- ▶ multicommodity flows
- ▶ value of communication
- ▶ resilience of networks with other dynamics